

Covariance-based spectrum sensing methods in practice

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Introduction

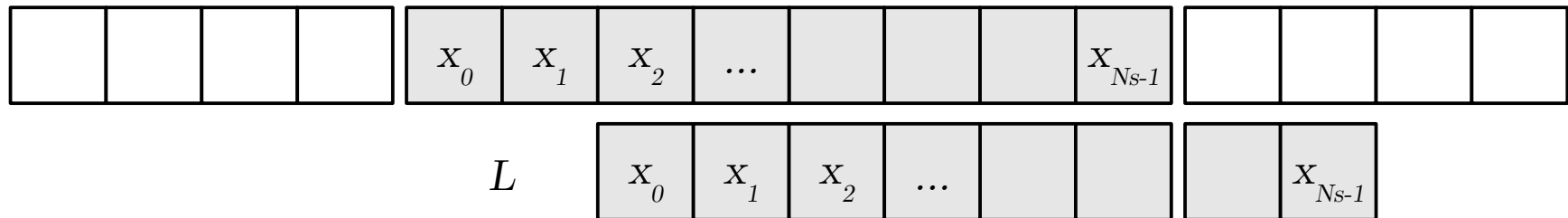
- A compact, low-cost spectrum sensor is desired.
 - Provides channel occupancy table to an agile radio.
 - Secondary usage of TVWS with consumer devices.
- Sample covariance-based methods (CBM)
 - Identified as a good compromise between implementation complexity, generality and sensing performance.
 - Simulations show good detection of typical transmissions in UHF band (e.g. legacy wireless microphones).
- Impact of realistic signal impairments is hard to predict theoretically.

Goals

- Compare CBM with energy detection (ED).
 - USRP, SNE-ESHTER as digital frontends for CBM and ED.
 - SNE-ISMTV-UHF as analog ED.
- Compare effect of different digital frontends.
 - USRP vs. SNE-ESHTER using same configuration
 - what are good design goals for a spectrum sensor?
- Assess feasibility of using constrained devices.
 - how well do CBM perform with low sample rates, low number of samples?

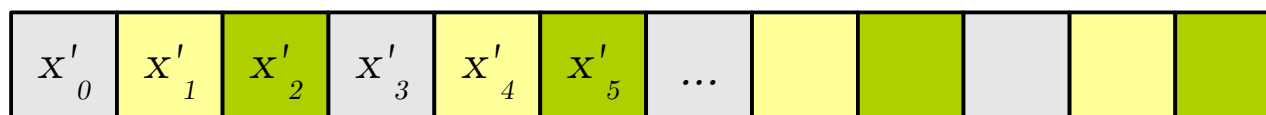
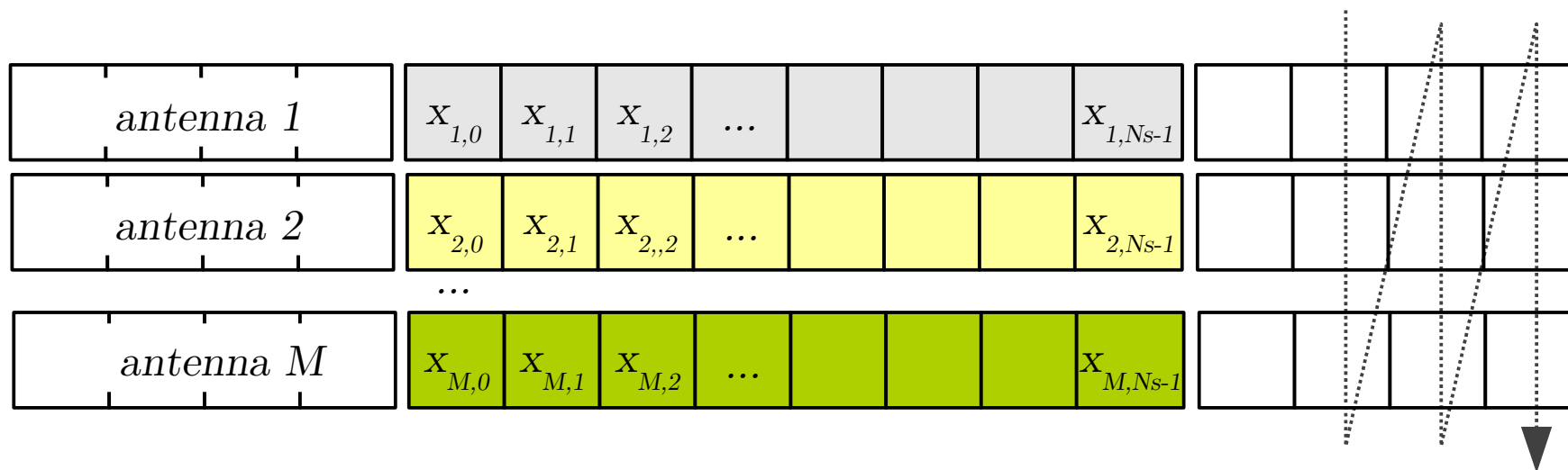
Covariance-based methods (CBM)

$$\sigma_l = \frac{1}{N_s} \sum_{n=0}^{N_s-1} x_n \cdot x_{n-l} \quad l \in [0, L-1]$$



$$\mathbf{R} = [r_{ij}] = \begin{bmatrix} \sigma_0 & \sigma_1 & \dots & \sigma_{L-1} \\ \sigma_1 & \sigma_0 & \dots & \sigma_{L-2} \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_{L-1} & \sigma_{L-2} & \dots & \sigma_0 \end{bmatrix}$$

Extension to M antennas



ML



$$\sigma_l = \frac{1}{MN_s} \sum_{n=0}^{MN_s-1} x'_n \cdot x'_{n-l} \quad l \in [0, ML-1]$$

(not tested in this experiment)

Simple CBM

$$\gamma = \frac{T_1}{T_2}$$

■ CAV

$$T_1 = \frac{1}{L} \sum_{i=1}^L \sum_{j=1}^L |r_{ij}| \quad T_2 = \frac{1}{L} \sum_{i=1}^L |r_{ii}|$$

■ CFN

$$T_1 = \frac{1}{L} \sum_{i=1}^L \sum_{j=1}^L |r_{ij}|^2 \quad T_2 = \frac{1}{L} \sum_{i=1}^L |r_{ii}|^2$$

■ MAC

$$T_1 = \max_{i \neq j} |r_{ij}| \quad T_2 = \frac{1}{L} \sum_{i=1}^L |r_{ii}|$$

Eigenvalue-based CBM

$$|\lambda_0| \geq |\lambda_1| \geq \dots \geq |\lambda_{L-1}|$$

■ MME

$$\gamma = \frac{|\lambda_0|}{|\lambda_{L-1}|}$$

■ AGM

$$\gamma = \frac{\frac{1}{L} \sum_{l=0}^{L-1} |\lambda_l|}{\sqrt[L]{\prod_{l=0}^{L-1} |\lambda_l|}}$$

■ EME

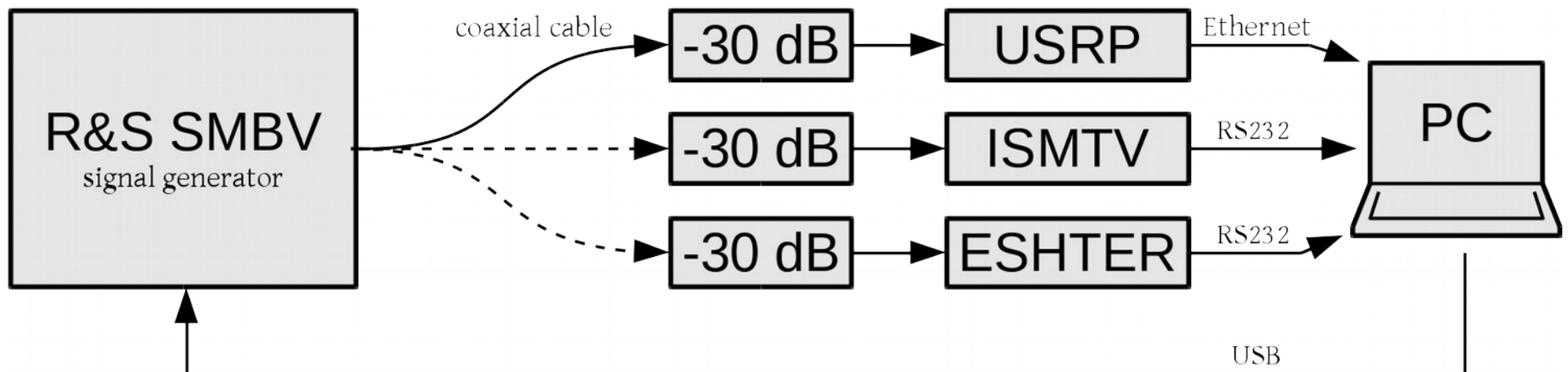
$$\gamma = \frac{\sum_{n=0}^{N_s-1} x_n^2}{\lambda_{L-1}}$$

■ MET

$$\gamma = \frac{|\lambda_0|}{\sum_{l=1}^L \lambda_l}$$

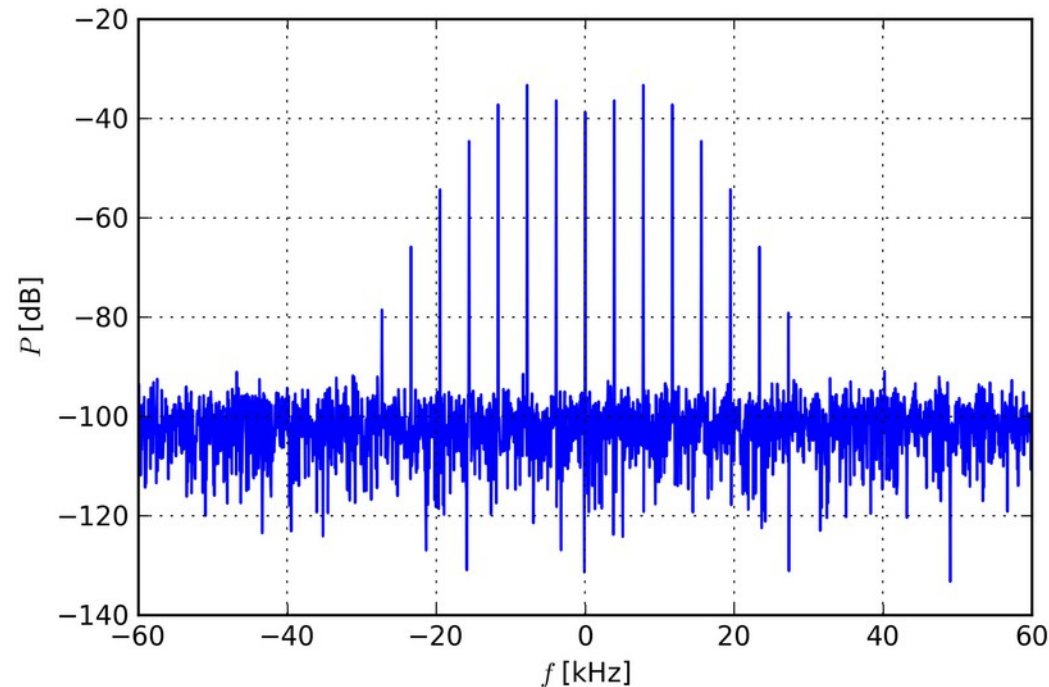
Experimental setup

- Rohde & Scharz SMBV100A vector signal generator
 - -30 dB attenuator (to protect against accidental overloads)
 - remotely controlled through USB
- Device under test
 - USRP N200 (SBX daughterboard)
 - VESNA sensor node (SNE-ISMTV and SNE-ESHTER radios)



Test signal

- tone-modulated FM carrier
 - “soft speaker” IEEE wireless microphone signal test vector



$$f_m = 3.9\text{kHz} \quad \Delta f = 15.0\text{kHz}$$

Test configurations

A) embedded profile

- e.g. ARM Cortex M3, single 1 Msample/s ADC, 96 kB RAM

B) embedded profile

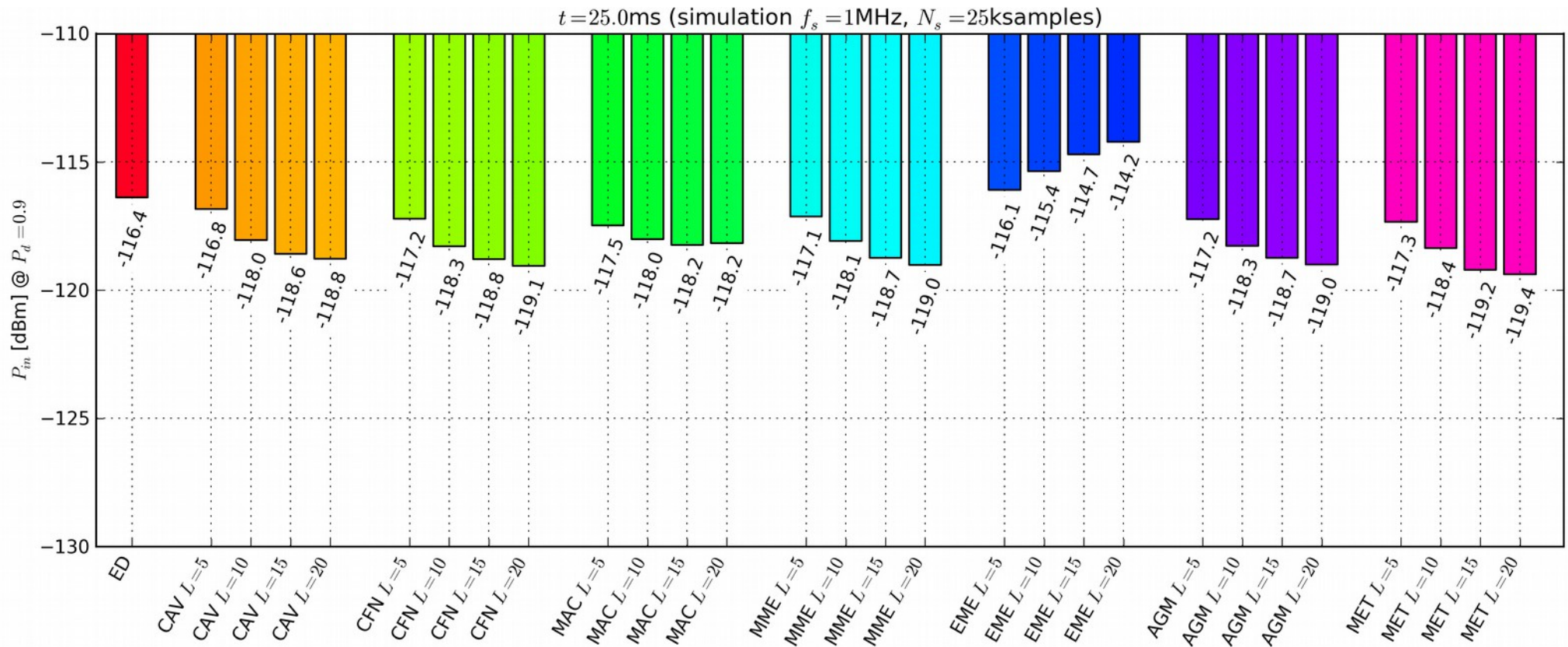
- e.g. ARM Cortex M3, dual 1 Msample/s ADCs, 96 kB RAM

C) high-end profile

	t_s [ms]	USRP		SNE-ISMTV-UHF	
		f_s [kHz]	N_s [samples]	f_s [kHz]	N_s [samples]
A	25.0	1,000	25,000	147	3,676
B	12.5	2,000	25,000	147	1,838
C	10.0	10,000	100,000	147	1,471

Simulation results

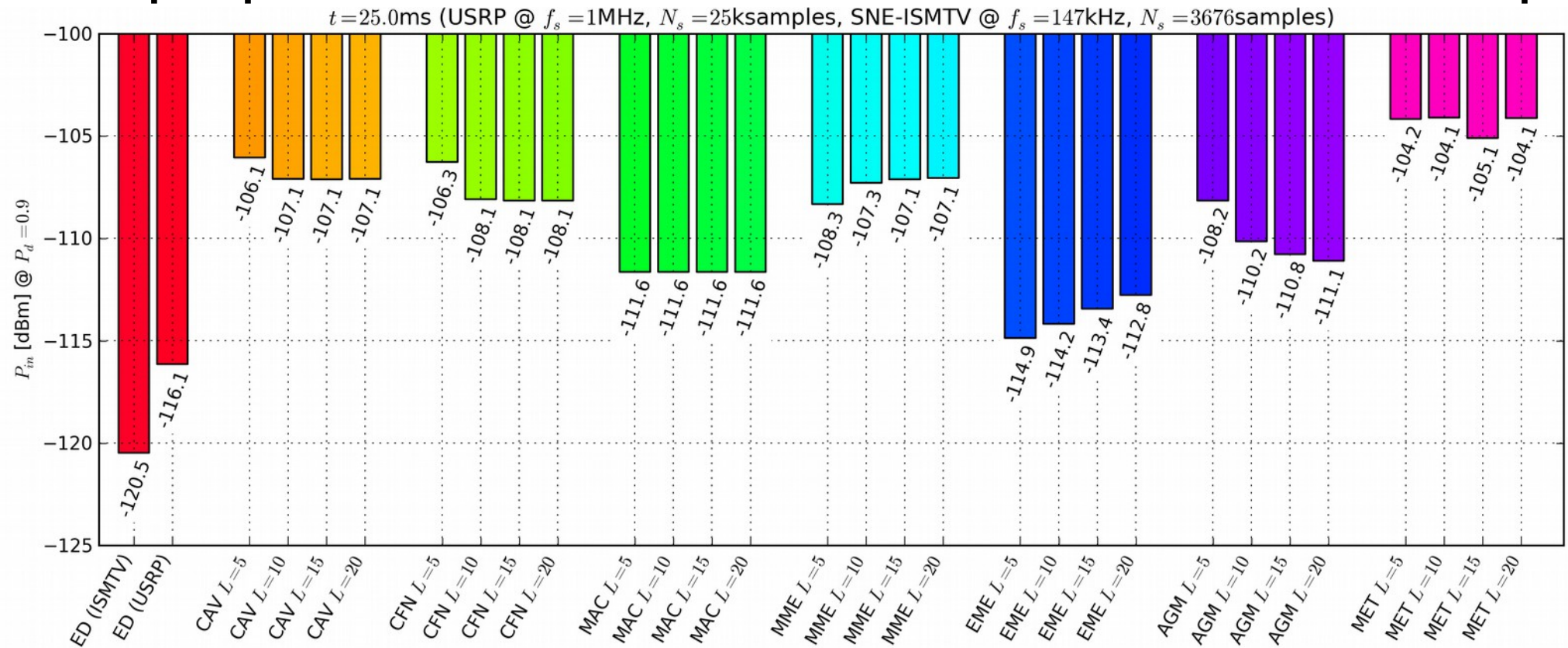
- Ideal signal waveform with AWGN.
- Ideal sampling, channel filtering, etc.



USRP & SNE-ISMTV-UHF

ED with SNE-ISMTV-UHF (analog), USRP (digital)

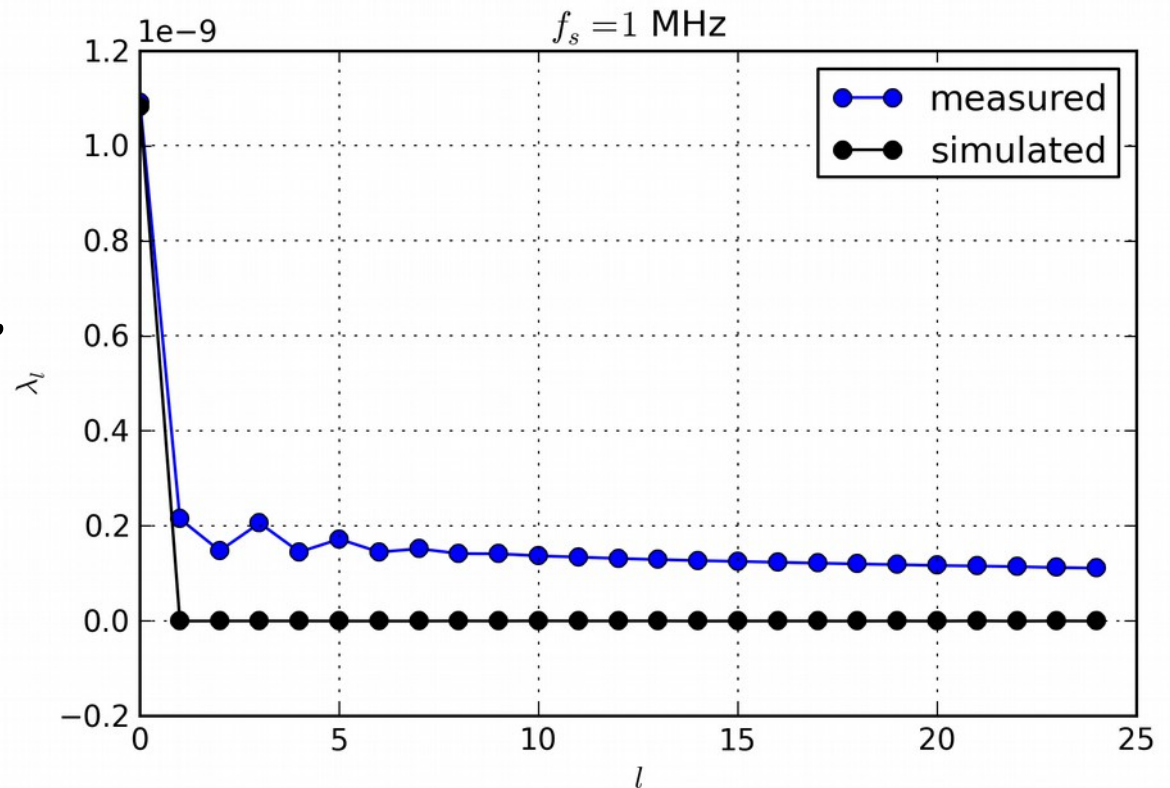
CBM with USRP



Explaining bad CBM performance

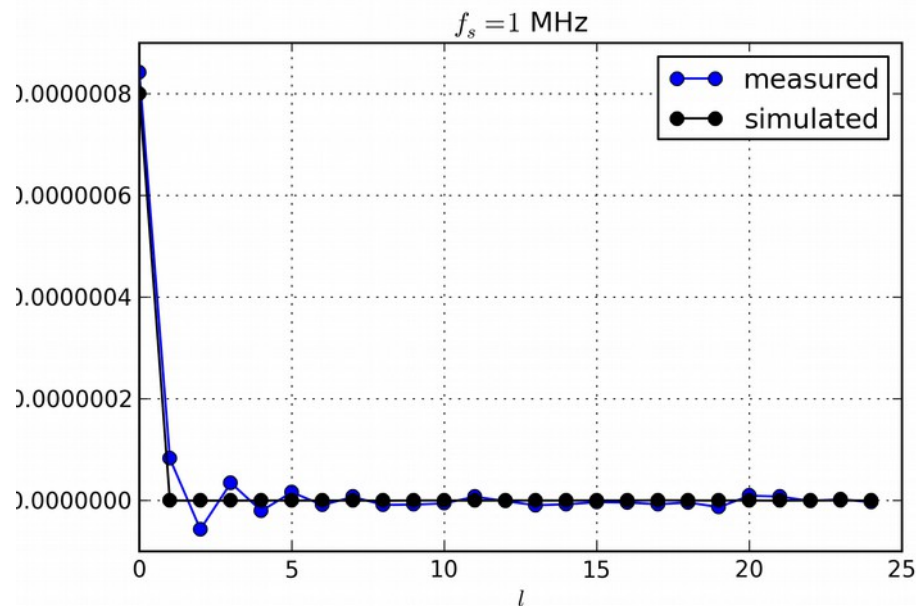
- USRP noise samples are already correlated.
- Compensation with Cholesky decomposition was not used.

- **Theory:** part of noise not Gaussian. (e.g. not due to linear filtering)



Immunity to noise level changes

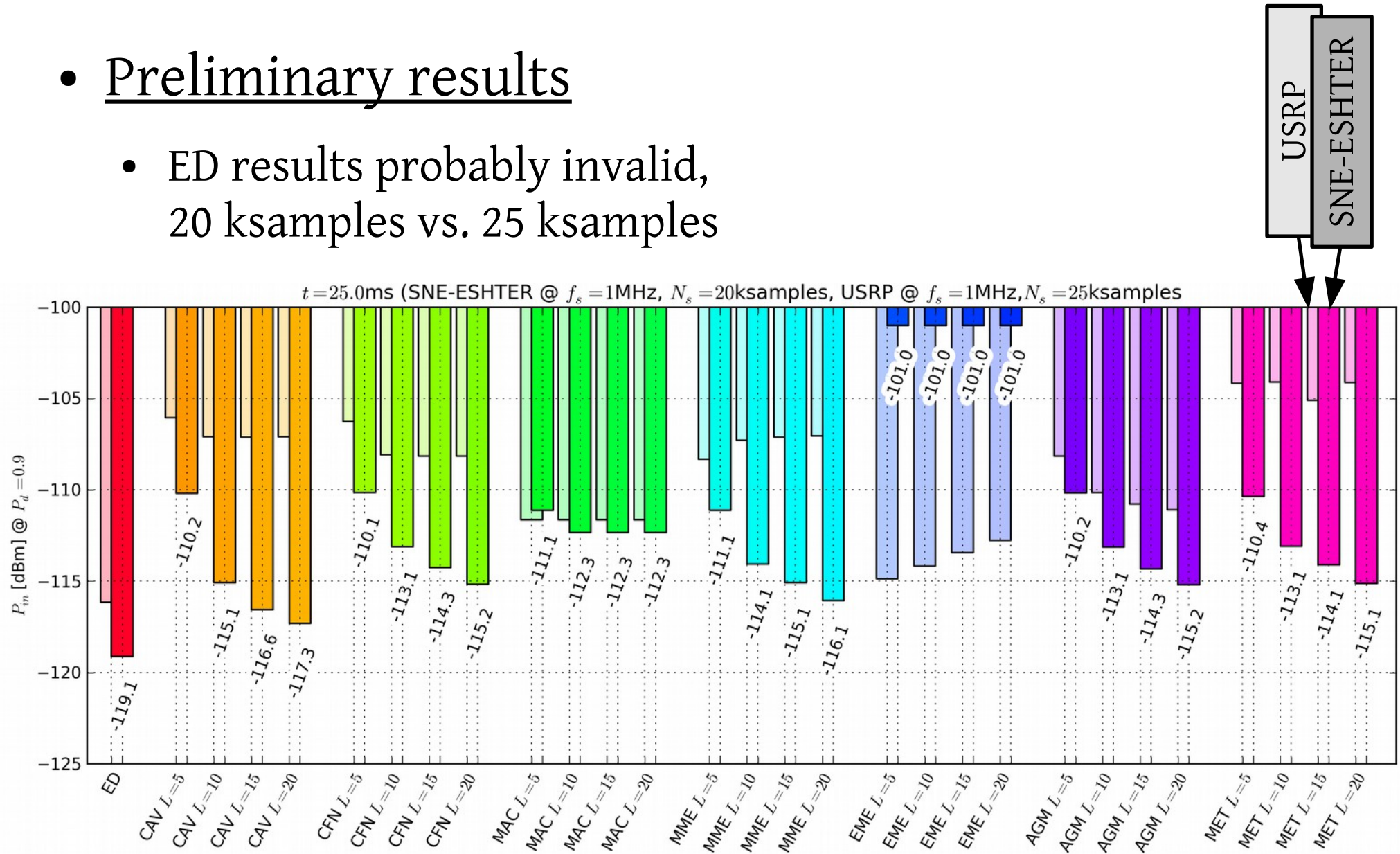
- Theory predicts that CBM should be immune to noise level changes
- Inject noise using the signal generator.



f_s N_s	1MHz 25ksamples	2MHz 25ksamples	10MHz 100ksamples
Method	$\Delta P_{noise} [\text{dB}] @ P_{fa} = 0.2$		
ED (USRP)	0.3	0.4	0.5
CAV $L = 5$	> 40.0	> 40.0	> 40.0
CAV $L = 10$	> 40.0	> 40.0	> 40.0
CAV $L = 15$	> 40.0	> 40.0	> 40.0
CAV $L = 20$	> 40.0	> 40.0	> 40.0
CFN $L = 5$	> 40.0	> 40.0	> 40.0
CFN $L = 10$	> 40.0	> 40.0	> 40.0
CFN $L = 15$	> 40.0	> 40.0	> 40.0
CFN $L = 20$	> 40.0	> 40.0	> 40.0
MAC $L = 5$	> 40.0	> 40.0	> 40.0
MAC $L = 10$	> 40.0	> 40.0	> 40.0
MAC $L = 15$	> 40.0	> 40.0	> 40.0
MAC $L = 20$	> 40.0	> 40.0	> 40.0
MME $L = 5$	> 40.0	> 40.0	> 40.0
MME $L = 10$	> 40.0	> 40.0	> 40.0
MME $L = 15$	> 40.0	> 40.0	> 40.0
MME $L = 20$	> 40.0	> 40.0	> 40.0
EME $L = 5$	> 40.0	2.2	> 40.0
EME $L = 10$	0.5	0.4	1.2
EME $L = 15$	0.4	0.4	0.9
EME $L = 20$	0.4	0.4	0.8
AGM $L = 5$	> 40.0	> 40.0	> 40.0
AGM $L = 10$	> 40.0	> 40.0	> 40.0
AGM $L = 15$	> 40.0	> 40.0	> 40.0
AGM $L = 20$	> 40.0	> 40.0	> 40.0
MET $L = 5$	> 40.0	> 40.0	> 40.0
MET $L = 10$	> 40.0	> 40.0	> 40.0
MET $L = 15$	> 40.0	> 40.0	> 40.0
MET $L = 20$	> 40.0	> 40.0	> 40.0

SNE-ESHTER compared to USRP

- Preliminary results
 - ED results probably invalid, 20 ksamples vs. 25 ksamples



Conclusions

- CBM detection threshold is worse than expected.
 - Assumption about uncorrelated noise samples is false.
 - Further work needed to find cause of noise correlation.
- Best performance for constrained device with MAC.
 - No noticeable benefits with Eigenvalue-based methods.
 - Higher smoothing factor does not always mean better performance.
- CBM are robust against changes in noise floor.
 - Simple energy detector outperforms CBM in practice if noise floor variance is not a factor.

Questions?

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